A Method for Calculating Turbulent Boundary Layers and Losses in the Flow Channels of Turbomachines

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ABSTRACT

An interactive inviscid core flow-boundary layer method is presented for the calculation of turbomachine channel flows. For this method, a one-dimensional inviscid core flow is assumed. The end-wall and blade surface boundary layers are calculated using an integral entrainment method. The boundary layers are assumed to be collateral and thus are two-dimensional. The boundary layer equations are written in a stream-line coordinate system. The streamwise velocity profiles are approximated by power law profiles. Compressibility is accounted for in the streamwise direction but not in the normal direction.

Equations are derived for the special cases of conical and two-dimensional rectangular diffusers. For these cases, the assumptions of a one-dimensional core flow and collateral boundary layers are valid. Results using the method are compared with experiment and good quantitative agreement is obtained.

NOMENCLATURE

 A_b unblocked flow area = $(1 - B) A_q$

Aq geometric area

A₁-A₃ terms in velocity gradient equation

a speed of sound

B blockage

b passage height

cf skin friction coefficient

c_p specific heat at constant pressure

 c_{pr} pressure recovery coefficient, $\frac{P - P_1}{P_1 e^{-P_1}}$

D diffuser throat diameter

 D_1-D_2 terms in velocity gradient equation

F entrainment function

H₁ shape factor, $\frac{\delta - \delta_1}{\delta_2}$

 H_2 shape factor, $\frac{\delta_1}{\delta_2}$

K1-K3 terms in area equation

K_t,K_V curvature terms

L diffuser length

M relative Mach number, W/a

Mu wheel speed Mach number, U/a

m exponent in velocity profile

m mass flux

P pressure

PSTD standard pressure, 101 325 N/m

Re Reynold's number

R_q gas constant

^ radius

s entropy

T temperature

TSTD standard temperature, 288.2 K

t tangential coordinate

U wheel speed

W relative velocity

x streamline coordinate

y normal coordinate

z blade number

 $\alpha \hspace{1cm} \text{angle between meridional streamline and} \\ \hspace{1cm} \text{axis of rotation}$

angle between relative velocity vector and meridional plane

γ specific heat ratio

δ boundary layer thickness

 δ_1 displacement thickness, $\int_0^{\delta} \left(1 - \frac{W}{W_e}\right) dy$

 δ_2 momentum thickness, $\int_0^{\delta} \frac{W}{W_e} \left(1 - \frac{W}{W_e}\right) dy$

θ channel divergence angle

λ prewhirl

μ coefficient of viscosity

ρ density

τ shear stress

 ϕ entropy function, $\int c_p \frac{dT}{T}$

w rotational speed

Subscripts:

A spanwise direction

e edge of boundary layer

r radial direction

t,T tangential direction

w wall

x streamline direction

y normal direction

1 channel inlet

2 channel exit

Superscripts

' absolute total conditions

" relative total conditions

INTRODUCTION

In the preliminary design of turbomachinery it is necessary to estimate the losses in the individual components. For rotors, stators and impellers, this is usually done by using empirical correlations for channel losses (e.g., skin friction, diffusion, etc. $(\underline{1-4})$). For diffusers (conical, rectangular) this is done by empirically relating the diffuser pressure recovery coefficient to the diffuser geometry and inlet flow conditions $(\underline{5,6})$. A more rigorous way of estimating these losses would be to calculate the surface boundary layers and from these obtain a massaveraged estimate of channel losses. However, many of the present methods for calculating boundary layers (e.g., the code, BLAYER, ref. 7) are not ideally suited for calculating the boundary layers in turbomachine flow channels.

First of all, most boundary layer codes are written for external flows, thus, they require a specification of the free-stream velocity distribution. For internal flows, the velocity distribution is not known apriori and thus must be determined by an iterative procedure along with the continuity equation for the assumed inviscid core flow. This can be a very time consuming procedure especially for preliminary design calculations where several levels of iteration must be performed.

Also, most boundary layer codes are written for two-dimensional flows along flat surfaces and thus ignore any coordinate curvature terms (i.e., metrics). This can lead to large errors for some internal channel flows in which the channel end walls are converging or diverging; e.g., nozzles and diffusers.

There have been several methods proposed to calculate the performance of straight-walled, rectangular type diffusers (8-11). These methods are all two-dimensional in nature (i.e., they ignore end-wall effects) and are limited to the computation of incompressible, straight center-line diffuser flows. These methods are highly developed and predict the performance of this class of diffusers very well even into the stalled regions of the diffuser maps. However, since all these methods are iterative, viscous-inviscid interaction methods, their running times can be much longer than that of the method proposed here. This could make them unsuitable for use in compressor preliminary design codes.

For these reasons, a noninterative integralentrainment method for calculating the flow fields in turbomachines has been developed. The method simultaneously calculates the free-stream velocity distribution from an assumed one-dimensional core flow continuity equation together with the equations describing the surface boundary layers. Thus, only one pass through the flow channel is required thereby making the method very fast. The primary assumptions made for the boundary layer calculations are that the flow is basically two-dimensional and that the boundary layer profile can be described by a power law. The exponent in the power law is allowed to vary as prescribed by the equations of motion. Compressibility is accounted for in the streamline direction but not in the direction normal to the flow surfaces. Turbulent flow is assumed everywhere using the semiempirical Ludwieg-Tillman relation for skin friction. Approximate methods for calculating through regions of fully-developed or separated flows are also presented. Comparisons are made with experimental data for the cases of conical and rectangular diffusers and good agreement is demonstrated for cases where no separation is indicated. Fair agreement is demonstrated in separated regions of the flow.

The method of analysis used to calculate the flow surface boundary layers in the channel is an integral-entrainment method. The method is similar to that used for the calculation of end-wall boundary layers in Ref. 12. For this analysis, the core flow is assumed to be one-dimensional and is described by the one-dimensional continuity and momentum equations.

Two-Dimensional Boundary Layer Method

The following assumptions are made for this analysis:

- (1) The flow is steady and turbulent everywhere
- (2) The fluid is a perfect gas
- (3) The flow in the boundary layers is two-dimensional, i.e., there is no crossflow component of velocity. Therefore, the boundary layers are also collateral, i.e., the flow angle, β, is constant through the boundary layer.
 - (4) The channel flow surfaces are adiabatic
- (5) There is no density variation in the direction normal to the channel boundaries although the density is allowed to vary in the streamline direction, i.e., $\rho = \rho(x)$. This approximation seems to work well for Mach numbers up to 1.0 and slightly beyond (12). For high supersonic flows, some other formulation would have to be used.
- (6) The boundary layer velocity profile in the streamline direction may be described by the power-law equation

$$\frac{W_{X}}{W_{Q}} = \left(\frac{Y}{\delta}\right)^{m} \tag{1}$$

where W_e , δ , and m are functions of distance along a streamline, x, only. The power law approximation adequately predicts pressure recovery up to separation, although the actual profile deviates from the power law approximation more significantly as separation is approached.

To completely solve the problem, the boundary layer thickness, δ , and the boundary layer exponent, m, for each surface boundary layer calculated; the free-stream velocity, $W_{\rm e}$; and the free-stream pressure, density and temperature must be determined. Thus, a total of (4 + 2n) equations must be solved where n is the number of surface boundary layers.

If a streamline coordinate system is chosen (with x in the streamline direction, y in the normal to the wall direction, and t in the crossflow direction completing the orthogonal triad), the boundary layer equations for motion can be written as follows:

Continuity

$$\frac{\partial (\rho W_X)}{\partial x} + \frac{\partial (\rho W_Y)}{\partial y} + \rho W_X (K_Y + K_t) = 0$$
 (2)

Momentum

$$\rho W_{x} \frac{\partial W_{x}}{\partial x} + \rho W_{y} \frac{\partial W_{x}}{\partial y} - \rho r \omega^{2} \sin \alpha \cos \beta = -\frac{\partial p}{\partial x} + \frac{1}{r} \frac{\partial (r \tau_{x})}{\partial y}$$
(3)

Normal Momentum

$$\frac{\partial p}{\partial y} = 0 \tag{4}$$

In Eq. (2), the curvature term, K_y , is defined as the curvature of the normal coordinate, y, in the t= constant plane and the curvature term, K_t , is defined as the curvature of the tangential coordinate, t, in the y= constant plane. The normal coordinate is assumed to be everywhere normal to the flow.

If Eqs. (2) and (3) are integrated through the boundary layer with the additional assumption that K_t , K_y , α , β and r are independent of the normal coordinate, γ ; the following equations result:

$$\int_{0}^{\delta} \frac{\partial (\rho W_{x})}{\partial x} dy + \int_{0}^{\delta} \frac{\partial (\rho W_{y})}{\partial y} dy + (K_{y} + K_{t}) \int_{0}^{\delta} \rho W_{x} dy = 0$$
(5)

$$\int_{0}^{\delta} \frac{\partial (\rho W_{X}^{2})}{\partial x} dy + \rho W_{e}W_{ye} + \rho (K_{y} + K_{t}) \int_{0}^{\delta} W_{X}^{2} dy$$

$$- \rho r \delta \omega^{2} \sin \alpha \cos \beta = - \delta \frac{\partial p}{\partial x} - \tau_{xm} \qquad (6)$$

Equation (3) can also be evaluated for the isentropic core flow which results in the following equation

$$\frac{dp}{dx} = -\rho W_e \frac{dW}{dx} + \rho r\omega^2 \sin \alpha \cos \beta$$
 (7)

One additional unknown was added in the integration of Eq. (3), i.e., the normal velocity at the edge of the boundary layer, W_{ye} , as shown in Eq. (6). This can be modelled using Head's entrainment relation as was demonstrated in Ref. 12. The resulting relation is given by

$$F = \frac{1}{W_e} \left(W_e \frac{d\delta}{dx} - W_{ye} \right) = 0.0306 (H_1 - 3)^{-0.653}$$
 (8)

Using the velocity profile from Eq. (1) and performing the indicated differentiations and integrations, Eqs. (5) to (8) can be combined to yield the following equations

$$\frac{dm}{dx} = -2m(1+m)(1+2m)\left[\frac{1}{W_e}\frac{dW_e}{dx} + \frac{F}{2\delta} - \frac{1+2m}{4m\delta}C_f\right]$$
(9)

$$\frac{1}{\delta} \frac{d\delta}{dx} = -\frac{(1 - M_e^2)}{W_e} \frac{dW_e}{dx} + \frac{1}{(1 + m)} \frac{dm}{dx} + (1 + m) \frac{F}{\delta}$$

$$-\frac{\sin\alpha\cos\beta}{r}M_u^2 - (K_y + K_t) \qquad (10)$$

Equations (9) and (10) can be solved if the variation in free stream velocity, $W_{\rm e}$, is known. A detailed derivation of equations similar to Eqs. (9) and (10) is shown in the Appendix to Ref. 12.

In order to solve these equations, the skin friction coefficient, $c_{\rm f}$, and the entrainment function, F, must be evaluated. The skin friction coefficient is obtained from the Ludwieg-Tillman relation which is

$$C_f = 0.246 \text{ Re}_{\delta_2}^{-0.268} e^{-1.561 \text{ H}_2}$$
 (11)

where $H_2 = 1 + 2m$.

The entrainment function is a function only of a boundary layer shape factor and was shown in Ref. 12 to be given by

$$F = 0.0306 \left(\frac{m}{1 - m}\right)^{0.653}$$
 (12)

The variation in the free stream velocity, W_e , can be determined if a one-dimensional core flow is assumed. In this case, the velocity can be determined from the continuity equation for the core flow which can be written

$$\dot{n} = \rho W_e A_b \tag{13}$$

where $\,{\rm A}_b\,$ represents the unblocked channel area normal to the flow.

Using the results from Eq. (7) and differentiating Eq. (13) results in the equation

$$\frac{1}{W_e} \frac{dW_e}{dx} = \frac{1}{(1 - M_e^2)} \left(-\frac{M_u^2 \sin \alpha \cos \beta}{r} - \frac{1}{A_b} \frac{dA_b}{dx} \right)$$
(14)

The static temperature of the core flow can be determined from the energy equation for the core flow which is

$$T = T'' - \frac{W_e^2}{2c_p} \tag{15}$$

where

$$T'' = T_1' - \frac{2\omega\lambda - (\omega r)^2}{2cp}$$
 (16)

The static pressure and density can then be determined from either Eq. (7) and the equation of state for the core flow, or from the isentropic relations for the core flow. These equations together with Eq. (14), and Eqs. (9) and (10) written for each boundary layer, then provide the (4 + 2n) equations needed to solve the channel flow field.

Fully Developed and Separated Flow

When the boundary layers from opposite walls of a channel merge, an isentropic core flow no longer exists and the flow is said to be fully developed. In this case, the thin shear layer assumption used in the derivation of Eqs. (2) to (4) is no longer valid. However, it would be useful to carry out the calculations after the flow becomes fully developed. In order to do this, some simplifying assumptions must be made. These are as follows:

(1) The boundary layer Eqs. (2) to (4) describe approximately the fully developed flow field.

(2) The centerline of the flow remains isentropic. Although this is consistent with Prandtl's mixing length theory of turbulence; in reality, it is not valid due to a nonzero shear stress gradient at the centerline.

With these assumptions and the fact that the entrainment function equals zero (as can be seen from the definition in Eq. (8)), and the boundary layer thickness equals half the channel height, Eqs. (9) and (14) can be solved as before.

It would also be useful to be able to continue the calculation beyond an indicated point of boundary layer separation. This point is usually determined by a limiting value of the shape factor, $H_2 = 1 + 2m$. Once again, the boundary layer Eqs. (2) to (4) become invalid when the boundary layer separates. Also, the assumed power law profiles cannot accurately describe a separated flow. However, calculations show that the pressure recovery and losses can be reasonably predicted using some simplifying assumptions. These are as follows:

(1) The boundary layer Eqs. (2) to (4) and power law profile remain valid for separated flow.

(2) The skin friction coefficient goes to zero.

(3) The entrainment function reaches a limiting value chosen to be the value at the separation point.

(4) The shape factor is allowed to increase

beyond the separation point.

With these assumptions, the calculations can proceed beyond points of separation or fully developed

Loss Calculations

Since the flow is assumed to be two-dimensional, the losses can be determined by a simple mass averaging procedure. Since the channel exit static pressure is determined in the solution of the boundary layer flow, all that is needed is a static enthalpy corresponding to a mass-averaged flow in the channel in order to calculate the mass-averaged entropy rise from the equation

$$s_2 - s_1 = \phi_2 - \phi_1 - R_g \ln \frac{\rho_2}{\rho_1}$$
 (17)

APPLICATIONS OF THE METHOD

The method has been applied to the cases of conical and rectangular diffusers. In these cases, the assumptions of a one-dimensional core flow and collateral boundary layers are valid at least for nonseparated flows.

Conical Diffuser

The basic geometry of a conical diffuser is shown in Fig. 1. In order to solve Eqs. (9), (10) and (14), the cross-sectional area, $A_{\rm b}$, and the curvatures, $K_{\rm y}$ and $K_{\rm t}$, must be determined. The flow area is assumed to lie on a spherical segment as shown which is approximately everywhere normal to the flow. The unblocked flow area is then given by

$$A_{b} = 2\pi x^{2} \left(1 - \cos\left[\theta - \frac{\delta_{1}}{x}\right]\right)$$
 (18)

and the area term in Eq. (14) becomes

$$\frac{1}{A_b} \frac{dA_b}{dx} = K_2 - K_1 \frac{d\delta_1}{dx}$$
 (19)

where
$$K_1 = \frac{\sin\left(\theta - \frac{\delta_1}{x}\right)}{x\left(1 - \cos\left(\theta - \frac{\delta_1}{x}\right)\right)}$$

$$K_2 = \frac{2}{x} + K_1 + \frac{\delta_1}{x}$$

The curvature terms for this case are given by

$$K_{y} = K_{t} = \frac{1}{x} = \frac{\sin \theta}{r}$$
 (20)

Then for this case, since $M_U = 0$, and

$$\frac{d\delta_1}{dx} = \frac{m}{1+m} \frac{d\delta}{dx} + \frac{\delta}{(1+m)^2} \frac{dm}{dx}$$
 (21)

Eq. (14) becomes

$$\frac{1}{W_{P}} \frac{dW_{P}}{dx} = \frac{A_{1}}{D_{1}}$$
 (22)

where
$$A_1 = -\frac{(2 + 3 K_1 \delta_1)}{x} - 2K_1 m^2 F + K_1 (1 + 2m)^2 \frac{c_f}{2}$$

$$D_1 = (1 - M_e^2)(1 + K_1 \delta_1) + 2K_1 \delta_1(1 + m)(1 + 2m)$$

Equations (9) and (10) complete the system of 3 equations in 3 unknowns (W_e ,m, δ). The equations are solved using a fourth-order Runge-Kutta technique (13).

Results using this method have been compared with experimental data from a wind-tunnel diffuser section (14) and with data for conical diffusers (5). Figures 2 to 4 show comparisons of velocity profiles, static pressure coefficients, and displacement thicknesses at the exit of the cross-leg diffuser of Ref. 14 for three different inlet Reynold's numbers and Mach numbers. In all cases the agreement is good. For these cases, the boundary layers remained attached according to the analysis. Figures 5(a) to (d) shows comparisons of pressure recovery coefficient for several arbitrary cases of inlet Mach number, blockage, and cone angle for the conical diffuser data of Ref. 5. Almost all of the data lie in a region where the flow would be expected to be separated according to the analysis. However, the agreement between experiment and analysis is still fair.

Rectangular Diffuser

The geometry for a rectangular diffuser is shown in Fig. 6. For this case, the boundary layers in the tangential (blade to blade) and spanwise (hub to shroud) directions cannot be assumed to be equal due to the fact that the initial boundary layer thicknesses may be unequal and the flow may become fully developed in one direction only. Thus, the tangential and spanwise boundary layers must be calculated separately. However, the core flow is still assumed to be one-dimensional.

The unblocked flow area for this case is given by

$$A_b = (b - 2\delta_{1A})(2\theta x - 2\delta_{1T})$$
 (23)

and the term in Eq. (12) becomes

$$\frac{1}{A_b} \frac{dA_b}{dx} = K_3 - K_2 \frac{d\delta_{1T}}{dx} - K_1 \frac{d\delta_{1A}}{dx}$$
 (24)

where

$$K_{1} = \frac{2}{(b - 2\delta_{1A})}$$

$$K_{2} = \frac{1}{(\theta x - \delta_{1T})}$$

$$K_{3} = \frac{\theta}{(\theta x - \delta_{1T})}$$

The curvature terms for the tangential boundary layers are given by

$$K_{y} = \frac{1}{x}; \quad K_{t} = 0$$
 (25)

The curvature terms for the spanwise boundary layers are given by

$$K_y = 0; K_t = \frac{1}{x}$$
 (26)

Equation (14) can then be expressed

$$\frac{1}{W_{e}} \frac{dW_{e}}{dx} = \frac{A_{1} + A_{2} + A_{3}}{D_{1} + D_{2}}$$
 (27)

where
$$A_1 = -2K_2 m_T^2 F_T - 2K_1 m_A^2 F_A$$

$$A_2 = \frac{K_2}{2} (1 + 2m_T)^2 c_{fT} + \frac{K_1}{2} (1 + 2m_A^2) c_{fA}$$

$$A_3 = -K_3 - K_2 \frac{\delta_1 T}{x} - K_1 \frac{\delta_1 A}{x}$$

$$D_1 = (1 - M_e^2) (1 + K_2 \delta_1 T + K_1 \delta_1 A)$$

$$D_2 = 2K_2 \delta_1 T (1 + m_T) (1 + 2m_T) + 2K_1 \delta_1 A (1 + m_A) (1 + 2m_A)$$

of 5 equations in 5 unknowns (We, ma, &a, mt, &t). Results using this method have been compared with experimental data for rectangular diffusers (6). A comparison of calculated and experimental pressure coefficients for several arbitrary cases of inlet Mach number, blockage, and divergence angle, 0, is shown in Fig. 7(a) to (d). The cases shown correspond to an inlet aspect ratio of one; however, the method is applicable for any arbitrary inlet aspect ratio. The cases were calculated assuming equal boundary layer thicknesses and exponents on the inlet vane surfaces and end walls. The results show fair agreement between calculation and experiment even though the calculations indicate that almost all of the data shown lie in a region where the flow would be separated.

CONCLUSIONS

An analytical method has been developed to cal-culate boundary layers and losses in turbomachine flow channels. Results using this method have been compared with experimental data for the special cases of conical and rectangular diffusers. Good agreement is demonstrated for the flow regimes where the analysis indicates no separation. Fair agreement is

demonstrated for the pressure coefficients calculated in the separated regions of the flow.

Since the method is a noninterative integral method, it is very fast compared to other methods of analysis. Thus, it can be easily adapted for use in preliminary design or off-design codes for turbo-machinery components.

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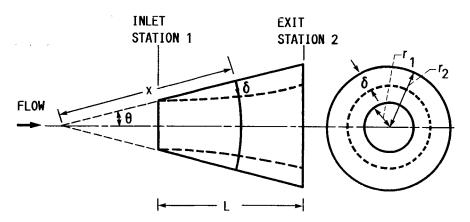


FIGURE 1.- CONICAL DIFFUSER GEOMETRY.

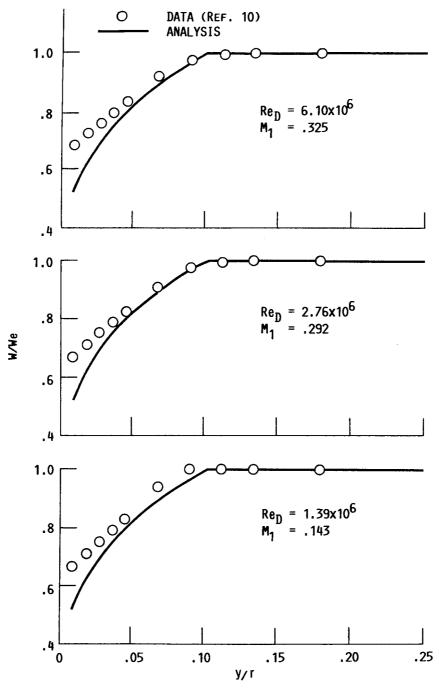


FIGURE 2.- BOUNDARY LAYER VELOCITY PROFILES AT EXIT OF .1 SCALE CROSSLEG DIFFUSER.

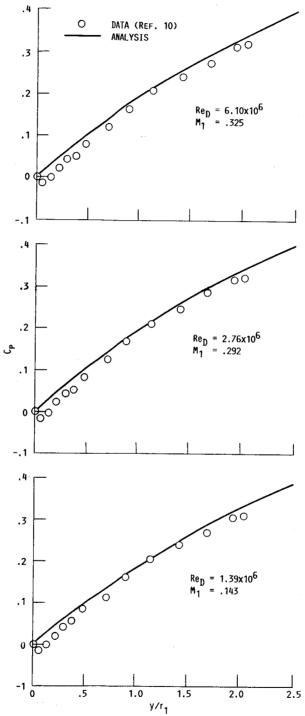


FIGURE 3.- PRESSURE RECOVERY COEFFICIENTS IN .1 SCALE CROSSLEG DIFFUSER.

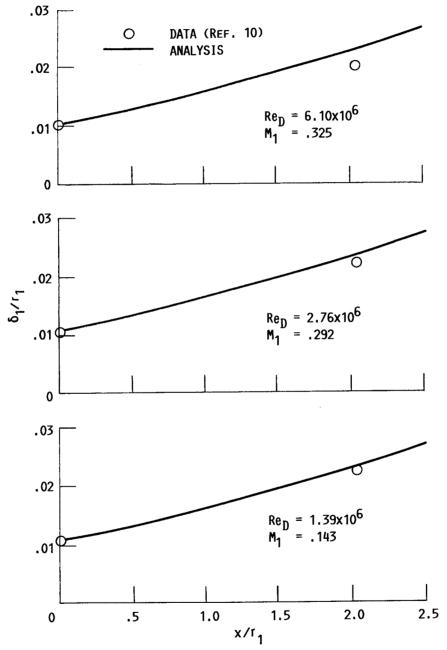


FIGURE 4.- DISPLACEMENT THICKNESSES IN .1 SCALE CROSSLEG DIFFUSER.

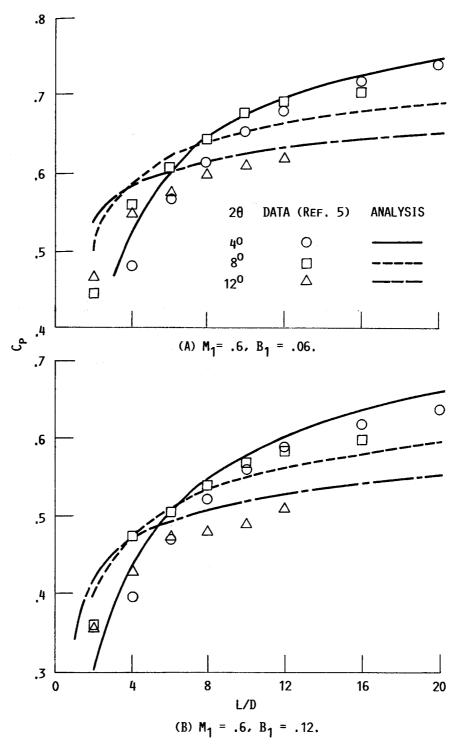
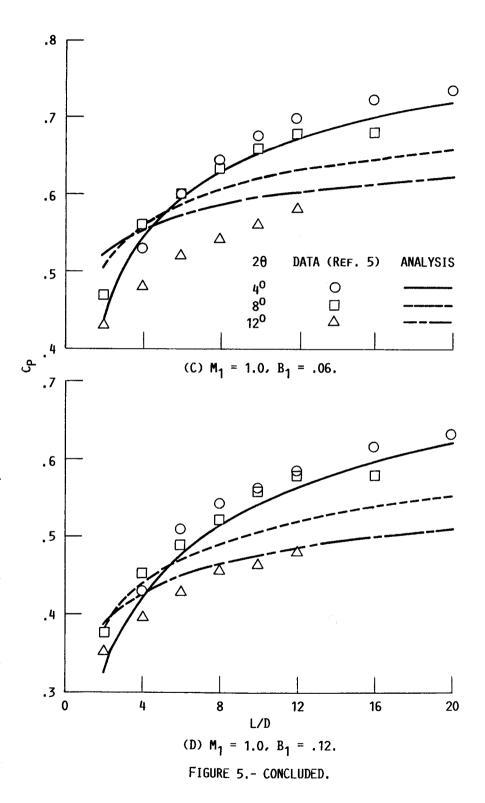


FIGURE 5.- PRESSURE RECOVERY COEFFICIENTS FOR VARIOUS CONICAL DIFFUSERS.



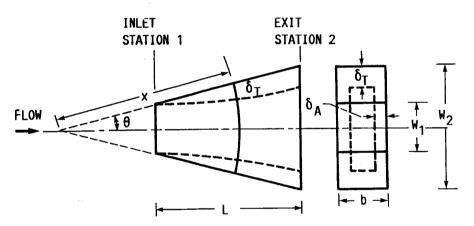


FIGURE 6.- RECTANGULAR DIFFUSER GEOMETRY.

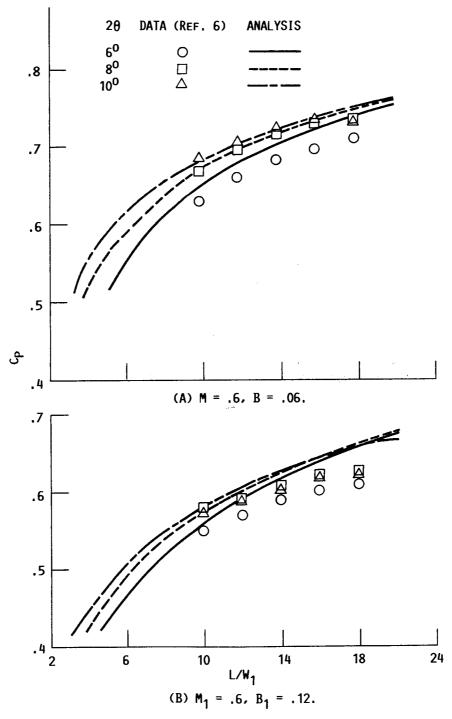
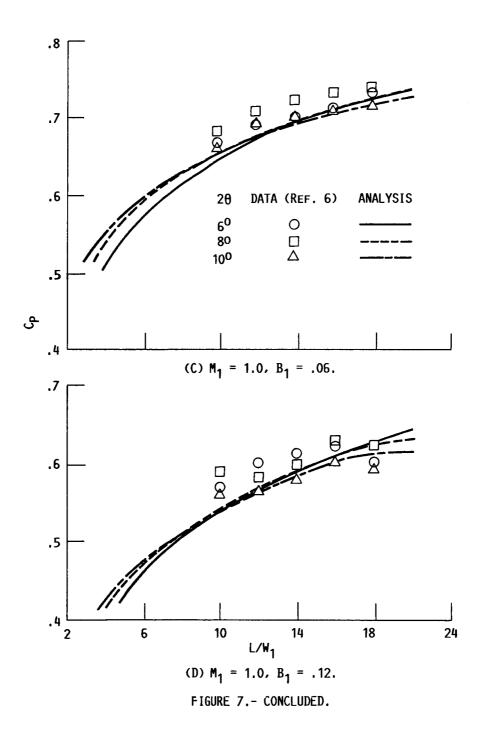


FIGURE 7.- PRESSURE RECOVERY COEFFICIENTS FOR VARIOUS RECTANGULAR DIFFUSERS.



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